# Supplementary information: full mathematical details to The Graetz-Nusselt problem extended to continuum flows with finite slip

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### 1 GOVERNING EQUATION

The Graetz-Nusselt problem considers transport of heat between a fluid and a tube, beginning at some location in the hydrodynamically developed flow region. The tube entrance length is unheated, and the wall temperature  $T_1$  of the heated or cooled section is constant but different from that of the entering fluid temperature  $T_0$ . The fluid has constant physical properties, and viscous dissipation and axial heat conduction are neglected. In this study we extend this classical problem to fluid flows with a finite slip velocity  $u_s$  at the wall at r = R. Wall slip can be quantified by a slip length b, which is defined according to Navier's slip condition,

$$u_s = -b \left. \frac{\partial u}{\partial r} \right|_{r=R}.$$
(1.1)

The governing equation describing stationary heat transport in such an axisymmetric cylindrical system, under the assumption of constant density  $\rho$  and thermal conductivity k, can be written as

$$u\frac{\partial T}{\partial x} = \frac{\alpha}{r}\frac{\partial}{\partial r}\left(r\frac{\partial T}{\partial r}\right),\tag{1.2}$$

where u(r,b) decribes the velocity profile of the laminar fluid flowing in the *x*-direction, and  $\alpha = k/(\rho C_p)$  is the thermal diffusivity. The initial and boundary condition are  $T(0,r) = T_0$  and  $T(x,R) = T_1$ .

Solving the Navier-Stokes equation for stationary slip flow in the axial direction, again assuming constant  $\rho$  and k, yields the following expression for the velocity profile,

$$\tilde{u} = \frac{2\left(1 - \tilde{r}^2\right) + 4\tilde{b}}{1 + 4\tilde{b}},$$
(1.3)

where  $\tilde{u} = u/u_{av}$ ,  $\tilde{r} = r/R$ , and  $\tilde{b} = b/R$ .  $\tilde{u}$  can written as the sum of the variable velocity  $\tilde{u}_v(\tilde{r}, \tilde{b})$  and the slip velocity  $\tilde{u}_s(\tilde{b})$  at the wall:

$$\tilde{u} = \tilde{u}_v + \tilde{u}_s = \frac{2(1 - \tilde{r}^2)}{1 + 4\tilde{b}} + \frac{4\tilde{b}}{1 + 4\tilde{b}}.$$
(1.4)

The governing heat equation can now be non-dimensionalised using  $\Theta = (T_1 - T)/(T_1 - T_0)$  and  $\tilde{x} = x/L$  (*L* being the length of the heated or cooled section of the pipe),

$$\frac{(1-\tilde{r}^2)+2\tilde{b}}{2(1+4\tilde{b})}\frac{\partial\Theta}{\partial\left(\tilde{x}/Gz\right)} = \frac{1}{\tilde{r}}\frac{\partial}{\partial\tilde{r}}\left(\tilde{r}\frac{\partial\Theta}{\partial\tilde{r}}\right),\tag{1.5}$$

with  $\Theta(0, \tilde{r}) = 1$  and  $\Theta(\tilde{x}, 1) = 0$ . The Graetz number Gz is defined as

$$Gz = RePr\frac{D}{L} = 4\frac{u_{av}R^2}{\alpha L},$$
(1.6)

where  $Re = u_{av}D/v$  is the Reynolds number,  $Pr = v/\alpha$  is the Prandtl number, and D is the diameter of the tube. For  $\tilde{x}/Gz < 0.01$  the fluid flow is thermally developing, while for  $\tilde{x}/Gz > 0.1$  the fluid flow is said to be thermally developed.

# **2** NUSSELT NUMBER

The local Nusselt number  $Nu_x$  is defined, by definition, as

$$Nu_x = \frac{h_x D}{k},\tag{2.1}$$

where  $h_x$  is the local heat transfer coefficient, being a function of the dimensionless position  $\tilde{x}/Gz$ . Following Newton's law of cooling and using Fourier's Law of thermal conduction, the heat transfer coefficient  $h_x$  can be rewritten as

$$h_x = \frac{q''}{\Delta T} = -\frac{k}{\langle T \rangle - T_1} \left. \frac{\partial T}{\partial r} \right|_{r=R},\tag{2.2}$$

where q" represents the local heat flux between the wall and the fluid. Rewriting the temperature gradient in dimensionless form gives

$$h_x = -\frac{2k}{D} \frac{1}{\langle \Theta \rangle} \left. \frac{\partial \Theta}{\partial \tilde{r}} \right|_{\tilde{r}=1},\tag{2.3}$$

where  $\langle \Theta \rangle = (T_1 - \langle T \rangle)/(T_1 - T_0)$ . Here, it is always true that  $\partial_{\bar{r}} \Theta \leq 0$ . Now,  $Nu_x$  can be written as

$$Nu_{x} = -\frac{2}{\langle \Theta \rangle} \left. \frac{\partial \Theta}{\partial \tilde{r}} \right|_{\tilde{r}=1}, \tag{2.4}$$

where  $\langle \Theta \rangle (\tilde{x}/Gz)$ . The dimensionless flow-averaged or mixing-cup temperature  $\langle \Theta \rangle$  can be calculated according to

$$\langle \Theta \rangle = \frac{\int_0^1 \Theta(\tilde{x}/Gz, \tilde{r})\tilde{u}(\tilde{r})\tilde{r}d\tilde{r}}{\int_0^1 \tilde{u}(\tilde{r})\tilde{r}d\tilde{r}}.$$
(2.5)

When  $\tilde{x}/Gz > 0.1$ ,  $Nu_x \rightarrow Nu_\infty$ .

# 3 LÉVÊQUE APPROXIMATION

#### 3.1 GOVERNING EQUATION AND VELOCITY PROFILE

To solve the temperature field near the very entrance of the pipe the Lévêque approximation is followed. This involves the following assumptions:

- curvature effects are neglected;
- infinite bulk is assumed;
- the velocity profile is regarded as linear, with the slope given by the slope of the velocity profile at the wall.

Then governing equation can be solved in Cartesian coordinates:

$$u\frac{\partial T}{\partial x} = \alpha \frac{\partial^2 T}{\partial y^2}.$$
(3.1)

The wall at r = R is now located at y = 0, *i.e.* the directions of the *r*- and *y*-axis are reversed. Under the assumptions listed above, the velocity profile can be writted as

$$\tilde{u} = \frac{4}{1+4\tilde{b}}(\tilde{y}+\tilde{b}),\tag{3.2}$$

where  $\tilde{y} = y/R$ .

Three different flow regimes can be distinguished:

- 1. no-slip, *i.e.*  $\tilde{b} = 0$  and hence  $\tilde{u} = 4\tilde{y}$ ;
- 2. finite slip, *i.e.*  $0 < \tilde{b} < \infty$ ;
- 3. no-shear, *i.e.*  $\tilde{b} = \infty$  and thus  $\tilde{u} = 1$ .

In the next sections an analytical expression for the local Nusselt number  $Nu_x$  is derived for each flow regime. In general,

$$Nu_x \propto \left(\frac{\tilde{x}}{Gz}\right)^{-\beta}$$
 (3.3)

The exponent  $\beta$  is constant for the two limiting cases and equals 1/3 for no-slip flow, and 1/2 for no-shear flow. In case of slip flow,  $\beta = f(\tilde{x}/Gz, \tilde{b})$ .

3.2 NO-SLIP

Making the governing energy equation dimensionless results in the following differential equation for no-slip flow,

$$Gz\tilde{y}\frac{\partial\Theta}{\partial\tilde{x}} = \frac{\partial^2\Theta}{\partial\tilde{y}^2},$$
(3.4)

with  $\Theta(0, \tilde{y}) = 1$ ,  $\Theta(\tilde{x}, 0) = 0$ , and  $\Theta(\tilde{x}, \infty) = 1$ .

By introducing a similarity variable  $\eta$ , where

$$\eta = \left(\frac{Gz\tilde{y}^3}{9\tilde{x}}\right)^{\frac{1}{3}},\tag{3.5}$$

and subsequent rewriting of the energy balance, we obtain the following ODE:

$$\frac{\mathrm{d}^2\Theta}{\mathrm{d}\eta^2} + 3\eta^2 \frac{\mathrm{d}\Theta}{\mathrm{d}\eta} = 0, \qquad (3.6)$$

with boundary conditions  $\Theta(0) = 0$  and  $\Theta(\infty) = 1$ . This ordinary differential equation has a known solution, and with the boundary conditions given the final solution for  $\Theta$  becomes

$$\Theta = \frac{1}{\Gamma(\frac{4}{3})} \int_0^{\eta} \exp(-\bar{\eta}^3) \,\mathrm{d}\bar{\eta}. \tag{3.7}$$

Previously, an expression for the Nusselt number was found using the dimensionless temperature gradient  $\partial_{\bar{r}}\Theta$ . Rewriting this in terms of  $\partial_{\bar{v}}\Theta$ , the expression for *Nu* becomes

$$Nu_{x} = \frac{2}{\langle \Theta \rangle} \left. \frac{\partial \Theta}{\partial \tilde{y}} \right|_{\tilde{y}=0}.$$
(3.8)

However, in the Lévêque approximation  $\langle \Theta \rangle = 1$ . Furthermore, the dimensionless temperature gradient is rewritten in terms of  $d_{\eta}\Theta$ . Then

$$Nu_{x} = \frac{2\eta}{\tilde{y}} \left. \frac{\mathrm{d}\Theta}{\mathrm{d}\eta} \right|_{\eta=0}.$$
(3.9)

Always the temperature gradient  $d_{\eta}\Theta > 0$ . Now, using the Leibniz formula for differentiation of integrals, an expression for the temperature gradient can be found:

$$\frac{\mathrm{d}\Theta}{\mathrm{d}\eta} = \frac{\exp(-\eta^3)}{\Gamma(\frac{4}{3})}.$$
(3.10)

Evaluating this at  $\eta = 0$  and substituting this in the expression for  $Nu_x$  we find

$$Nu_x = \frac{2}{\Gamma(\frac{4}{3})} \frac{\eta}{\tilde{y}},\tag{3.11}$$

or,

$$Nu_{x} = \frac{2}{9^{\frac{1}{3}}\Gamma(\frac{4}{3})} \left(\frac{\tilde{x}}{Gz}\right)^{-\frac{1}{3}}.$$
(3.12)

Thus, we find that for the no-slip regime the exponent is  $\beta = 1/3$ .

#### 3.3 NO-SHEAR

For the no-shear case, which implies that we have plug flow, the velocity profile is uniform. Rewriting the governing equation yields the following dimensionless PDE:

$$\frac{G_z}{4}\frac{\partial\Theta}{\partial\tilde{x}} = \frac{\partial^2\Theta}{\partial\tilde{y}^2},\tag{3.13}$$

with  $\Theta(0, \tilde{y}) = 1$ ,  $\Theta(\tilde{x}, 0) = 0$ , and  $\Theta(\tilde{x}, \infty) = 1$ . Using the similarity variable

$$\eta = \left(\frac{Gz\tilde{y}^2}{16\tilde{x}}\right)^{\frac{1}{2}},\tag{3.14}$$

this PDE turns into the following ODE having a known solution,

$$\frac{\mathrm{d}^2\Theta}{\mathrm{d}\eta^2} + 2\eta \frac{\mathrm{d}\Theta}{\mathrm{d}\eta} = 0, \qquad (3.15)$$

with  $\Theta(0) = 0$  and  $\Theta(\infty) = 1$ . Solving this ODE gives

$$\Theta = \frac{2}{\sqrt{\pi}} \int_0^{\eta} \exp(-\bar{\eta}^2) \,\mathrm{d}\bar{\eta} = \operatorname{erf}(\eta). \tag{3.16}$$

In order to find an expression for  $Nu_x$ , we need an equation for the temperature gradient. This is

$$\frac{\mathrm{d}\Theta}{\mathrm{d}\eta} = \frac{2}{\sqrt{\pi}} \exp(-\eta^2). \tag{3.17}$$

Ultimately this results in the following expression for  $Nu_x$ :

$$Nu_x = \frac{1}{\sqrt{\pi}} \left(\frac{\tilde{x}}{Gz}\right)^{-\frac{1}{2}}.$$
(3.18)

Here,  $\beta = 1/2$ .

## 3.4 FINITE SLIP

To find an analytical expression for  $Nu_x$  for fluid flow with finite slip, we start by rewriting the expression for the velocity profile:

$$u = 4u_{av}\frac{y+b}{R+4b}.$$
(3.19)

Plugging this into the governing equation for heat transport, and using the dimensionless variables T = T

$$\Theta = \frac{T_1 - T}{T_1 - T_0},\tag{3.20}$$

$$Y = \frac{y}{b},\tag{3.21}$$

$$X = x \frac{\alpha(R+4b)}{4u_{av}b^3},\tag{3.22}$$

we can non-dimensionalize the governing equation. This yields

$$(1+Y)\frac{\partial\Theta}{\partial X} = \frac{\partial^2\Theta}{\partial Y^2},\tag{3.23}$$

with  $\Theta(0,Y) = 1$ ,  $\Theta(X,0) = 0$ , and  $\Theta(X,\infty) = 1$ . To reduce the number of variables, we perform a Laplace transformation of  $\partial_X \Theta$  in *X*,

$$\mathscr{L}_{X}\left[\frac{\partial\Theta}{\partial X}\right] = \int_{0}^{\infty} \frac{\partial\Theta}{\partial X} e^{-pX} \, \mathrm{d}X = p\bar{\Theta}(p,Y) - \Theta(0,Y) = p\bar{\Theta}(p,Y) - 1, \qquad (3.24)$$

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where  $\overline{\Theta}$  is the Laplace transform of  $\Theta$ ,

$$\bar{\Theta}(p,Y) = \mathscr{L}_X[\Theta] = \int_0^\infty \Theta(X,Y) e^{-pX} \, \mathrm{d}X.$$
(3.25)

Furthermore,

$$\mathscr{L}_X\left[\frac{\partial^2 \Theta}{\partial Y^2}\right] = \frac{\partial^2 \bar{\Theta}}{\partial Y^2}.$$
(3.26)

The governing equation now becomes

$$(1+Y)(p\bar{\Theta}-1) = \frac{\partial^2 \bar{\Theta}}{\partial Y^2},$$
(3.27)

with  $\overline{\Theta}(p,0) = 0$  and  $\overline{\Theta}(p,\infty) = 1/p$ . To convert this into an ODE with a known solution, we change variable by introducing

$$\hat{\Theta} = \bar{\Theta} - \frac{1}{p}.$$
(3.28)

Now we obtain

$$p(1+Y)\hat{\Theta} = \frac{\partial^2 \hat{\Theta}}{\partial Y^2}$$
(3.29)

with  $\hat{\Theta}(p,0) = -1/p$  and  $\hat{\Theta}(p,\infty) = 0$ . Now we change variable a second time by defining

$$\eta = p^{1/3}(1+Y). \tag{3.30}$$

Following Faà di Bruno's formula for second order derivatives saying

$$\frac{\partial^2 \hat{\Theta}}{\partial Y^2} = \frac{\partial^2 \hat{\Theta}}{\partial \eta^2} \left(\frac{\partial \eta}{\partial Y}\right)^2 + \frac{\partial \hat{\Theta}}{\partial \eta} \frac{\partial^2 \eta}{\partial Y^2},\tag{3.31}$$

we find

$$\frac{\mathrm{d}^2\hat{\Theta}}{\mathrm{d}\eta^2} - \eta\hat{\Theta} = 0 \tag{3.32}$$

with  $\hat{\Theta}(p^{1/3}) = -1/p$  and  $\hat{\Theta}(\infty) = 0$ . This ODE is known as the Airy equation, whose general solution of the first kind is the Airy function Ai $(\eta)$ ,

$$\operatorname{Ai}(\eta) = \frac{1}{2\pi i} \int_{-i\infty}^{+i\infty} \exp\left(\eta z - \frac{z^3}{3}\right) \, \mathrm{d}z, \qquad (3.33)$$

or,

$$\operatorname{Ai}(\eta) = \frac{1}{\pi} \int_0^\infty \cos\left(\eta z + \frac{z^3}{3}\right) \, \mathrm{d}z,\tag{3.34}$$

with  $\lim_{\eta\to\infty} Ai(\eta) = 0$ . Then the solution for  $\hat{\Theta}$  becomes

$$\hat{\Theta} = -\frac{\operatorname{Ai}(p^{1/3}(1+Y))}{p\operatorname{Ai}(p^{1/3})},$$
(3.35)

and

$$\bar{\Theta} = \frac{\operatorname{Ai}(p^{1/3}) - \operatorname{Ai}(p^{1/3}(1+Y))}{p\operatorname{Ai}(p^{1/3})}.$$
(3.36)

This expression for  $\overline{\Theta}$  recovers both  $\overline{\Theta}(p,0) = 0$  and  $\overline{\Theta}(p,\infty) = 1/p$ . To obtain  $\Theta$ , we take the inverse Laplace transform in *X*, giving

$$\Theta(X,Y) = \mathscr{L}_X^{-1}\left[\bar{\Theta}\right] = \frac{1}{2\pi i} \int_{c-i\infty}^{c+i\infty} \frac{\operatorname{Ai}(p^{1/3}) - \operatorname{Ai}(p^{1/3}(1+Y))}{p\operatorname{Ai}(p^{1/3})} e^{pX} \,\mathrm{d}p.$$
(3.37)

For  $Nu_x$  we can derive that

$$Nu_{x} = \frac{2}{\tilde{b}} \left. \frac{\partial \Theta}{\partial Y} \right|_{Y=0}, \tag{3.38}$$

where, following Leibniz' integral rule,

$$\frac{\partial \Theta}{\partial Y} = -\frac{1}{2\pi i} \int_{c-i\infty}^{c+i\infty} \frac{\operatorname{Ai}'(p^{1/3}(1+Y))e^{pX}}{p^{2/3}\operatorname{Ai}(p^{1/3})} \,\mathrm{d}p.$$
(3.39)

Then, finally, we obtain

$$Nu_{x} = -\frac{1}{\tilde{b}\pi i} \int_{c-i\infty}^{c+i\infty} \frac{\operatorname{Ai}'(p^{1/3})e^{pX}}{p^{2/3}\operatorname{Ai}(p^{1/3})} \,\mathrm{d}p,$$
(3.40)

or

$$Nu_x = \frac{2}{\tilde{b}}g(X), \tag{3.41}$$

with

$$g(X) = -\frac{1}{2\pi i} \int_{c-i\infty}^{c+i\infty} \frac{\operatorname{Ai}'(p^{1/3})e^{pX}}{p^{2/3}\operatorname{Ai}(p^{1/3})} \,\mathrm{d}p.$$
(3.42)

X turns out to be a function of  $\tilde{x}/Gz$  and  $\tilde{b}$ , as

$$X = \frac{x}{L} \frac{\alpha L}{4u_{av}R^2} \frac{R^2(R+4b)}{b^3} = \left(\frac{\tilde{x}}{Gz}\right) \frac{1+4\tilde{b}}{\tilde{b}^3}.$$
 (3.43)

The function g(X) is universal, as it does not depend on the slip length b. The slip length affects the scaling between X and  $\tilde{x}/Gz$ , so it determines with part of the function g(X) is relevant. When  $\tilde{b} \to 0, X \to \infty$ , while for  $\tilde{b} \to \infty, X \to 0$ . As a check, when  $\tilde{b} \to 0$  we expect that

$$g(X) \propto X^{-1/3}$$
 (3.44)

for large X. Then

$$Nu_x \propto \frac{1}{\tilde{b}} \left(\frac{\tilde{x}}{Gz} \frac{1}{\tilde{b}^3}\right)^{-1/3} = \left(\frac{\tilde{x}}{Gz}\right)^{-1/3}.$$
(3.45)

When  $\tilde{b} \rightarrow \infty$  we expect that

$$g(X) \propto X^{-1/2}$$
 (3.46)

for small X. Then

$$Nu_x \propto \frac{1}{\tilde{b}} \left(\frac{\tilde{x}}{Gz} \frac{4\tilde{b}}{\tilde{b}^3}\right)^{-1/2} = \left(\frac{\tilde{x}}{Gz}\right)^{-1/2}.$$
(3.47)

To evaluate g(X), let  $p = s^3$ . Then

$$g(X) = -\frac{1}{2\pi i} \int_{c-i\infty}^{c+i\infty} \frac{\operatorname{Ai}'(s)e^{s^3X}}{s^2\operatorname{Ai}(s)} 3s^2 \, \mathrm{d}s = -\frac{3}{2\pi i} \int_{c-i\infty}^{c+i\infty} \frac{\operatorname{Ai}'(s)e^{s^3X}}{\operatorname{Ai}(s)} \, \mathrm{d}s.$$
(3.48)

The integral should start in the sector  $-\pi/2 < \arg(s) < -\pi/6$  and finish in the sector  $\pi/6 < \arg(s) < \pi/2$ . The convergence properties of the integrand are best if we integrate along the rays  $\arg(s) = \pm \pi/3$ . On the ray  $\infty e^{-i\pi/3}$  to the origin we let  $s = ke^{-i\pi/3}$  with k going from  $\infty$  to 0. On the ray from the origin to  $\infty e^{i\pi/3}$  we let  $s = ke^{i\pi/3}$  with k going from 0 to  $\infty$ . Thus

$$g(X) = -\frac{3e^{-i\pi/3}}{2\pi i} \int_{\infty}^{0} \frac{\operatorname{Ai}'(ke^{-i\pi/3})e^{-k^{3}X}}{\operatorname{Ai}(ke^{-i\pi/3})} \, \mathrm{d}k - \frac{3e^{i\pi/3}}{2\pi i} \int_{0}^{\infty} \frac{\operatorname{Ai}'(ke^{i\pi/3})e^{-k^{3}X}}{\operatorname{Ai}(ke^{i\pi/3})} \, \mathrm{d}k, \tag{3.49}$$

or

$$g(X) = \frac{3e^{-5i\pi/6}}{2\pi} \int_0^\infty \frac{\operatorname{Ai}'(ke^{-i\pi/3})e^{-k^3X}}{\operatorname{Ai}(ke^{-i\pi/3})} \, \mathrm{d}k + \frac{3e^{5i\pi/6}}{2\pi} \int_0^\infty \frac{\operatorname{Ai}'(ke^{i\pi/3})e^{-k^3X}}{\operatorname{Ai}(ke^{i\pi/3})} \, \mathrm{d}k.$$
(3.50)

The integrand decays rapidly and can be evaluated numerically. In FIG. 3.1 the function g(X) is plotted as function of X. As demonstrated in the graph, the limiting behaviour of g(X) is as expected: when  $X \to 0$ ,  $g(X) \propto X^{-1/2}$ , and when  $X \to \infty$ ,  $g(X) \propto X^{-1/3}$ .  $\beta$ , as obtained by computing the gradient of  $\log_{10}(Nu_x)$  versus  $\log_{10}(\tilde{x}/Gz)$ , is plotted in FIG. 3.2.  $\beta \approx 5/12$  when X = 1. Thus, the dimensionless group X can be considered as a kind of criterion for the behaviour of  $\beta: \beta \to 1/2$  when  $X \ll 1$ , whereas  $\beta \to 1/3$  when  $X \gg 1$ .

The expression

$$G(X) = \frac{0.546 \left(X^{1/2.420} + 1.058\right)^{2.420/6}}{X^{1/2}}$$
(3.51)

is a good approximation to g(X), which is accurate to about 0.5% for  $10^{-4} < X < 10^4$ .



Figure 3.1: g(X) as function of *X*.



Figure 3.2:  $\beta$  as function of *X* as obtained from g(X).

#### **4** NUMERICAL PROCEDURE

Numerically, the Graetz-Nusselt problem for finite slip was solved using the pdepe-solver in MATLAB. It is required that the equation to be solved has the following form:

$$c\left(\tilde{r},\tilde{x}/Gz,\Theta,\frac{\partial\Theta}{\partial\tilde{r}}\right)\frac{\partial\Theta}{\partial(\tilde{x}/Gz)} = \tilde{r}^{-m}\frac{\partial\Theta}{\partial\tilde{r}}\left[\tilde{r}^{m}f\left(\tilde{r},\tilde{x}/Gz,\Theta,\frac{\partial}{\partial\tilde{r}}\right)\right] + s\left(\tilde{r},\tilde{x}/Gz,\Theta,\frac{\partial\Theta}{\partial\tilde{r}}\right).$$
(4.1)

In this study,  $c = \tilde{u}/4$ ,  $f = \partial_{\bar{r}}\Theta$ , and s = 0. The value of *m* depends on the coordinate system chosen to solve the equation. For cylindrical coordinates m = 1. The initial and boundary conditions were defined according to

$$\Theta\left(\tilde{r}, (\tilde{x}/Gz)_0\right) = \Theta_0\left(\tilde{r}\right) = 1, \tag{4.2}$$

and

$$p\left(\tilde{r},\tilde{x}/Gz,\Theta\right) + q\left(\tilde{r},\tilde{x}/Gz,\right)f\left(\tilde{r},\tilde{x}/Gz,\Theta,\frac{\partial\Theta}{\partial\tilde{r}}\right) = 0.$$
(4.3)

For the boundary condition  $\Theta(1,\tilde{x}/Gz) = 0$ ,  $p = \Theta(1,\tilde{x}/Gz)$  and q = 0. Furthermore, for  $\partial_{\tilde{r}}\Theta(0,\tilde{x}/Gz) = 0$ , p = 0 and q = 1. However, boundedness of the solution near  $\tilde{r} = 0$  requires that the flux f vanishes at  $\tilde{r} = 0$ . For m > 0, pdepe imposes this boundary condition automatically and it ignores values specified for p and q. The relative and absolute tolerance for the pdepe-solver were set at respectively  $10^{-6}$  and  $10^{-12}$ . For calculating  $\partial_{\tilde{r}}\Theta$  at  $\tilde{r} = 1$  the MATLAB-function pdeval was utilised.

Because heat transport mainly occurs near the inlet and near the wall, the  $\tilde{x} \times \tilde{r} = 82 \times 101$ -mesh was refined near these boundaries. For  $\tilde{x} = 0$ , the MATLAB logspace-script was used to create an logarithmically equally spaced grid in the *x*-direction. Refinement in the  $\tilde{r}$ -direction was obtained by using a linearly spaced vector (linspace) for  $\tilde{r}_0$  and the following expression:

$$\tilde{r} = 1 - \left[ 0.99(1 - \tilde{r}_0^2) + 0.01(1 - \tilde{r}_0) \right].$$
(4.4)

The values for  $\beta_f$  in the thermally developing regime were obtained by fitting a straight line through  $\log_{10}(Nu_x)$  for  $-7 \leq \log_{10}(\tilde{x}/Gz) \leq -4$  using the polyfit-algorithm.<sup>1</sup>  $\beta_l$  is the gradient of  $\log_{10}(Nu_x)$  or  $\log_{10}(g(X))$  versus  $\log_{10}(\tilde{x}/Gz)$ , computed using the 2nd order accurate gradient-algorithm.  $Nu_{\infty}$  is taken as the average of  $Nu_x$  for  $\tilde{x}/Gz \geq 0.1$ . To compute the flowaveraged or mixing-cup temperature  $\langle \Theta \rangle$  the trapz-script was utilised. Gradients of  $\beta$  and  $Nu_{\infty}$ versus  $\tilde{b}$  were calculated using the gradient-algorithm.

The thermal boundary thickness  $\tilde{\lambda}_T$  was calculated numerically from the temperature profile, which was approximated by linear intrapolation of the temperature to find  $\tilde{r}(\Theta = 0.99)$  using two the temperature points closest to  $\Theta = 0.99$ .

<sup>&</sup>lt;sup>1</sup>Note that changing the range of  $\tilde{x}/Gz$ -values used to compute  $\beta_f$  results in a different transition point for  $\beta_f$ . Using larger values shifts the transition point upwards. Nonetheless, the distance between the transition points for  $\beta_f$  and  $Nu_{\infty}$  remains at least one order of magnitude large. When using  $-7 \le \log_{10}(\tilde{x}/Gz) \le -4$ , the transition point for  $\beta_f$  is located at  $\tilde{b} = 1.5 \times 10^{-2}$ . This point is located at  $\tilde{b} = 0.7 \times 10^{-2}$  when using  $-7 \le \log_{10}(\tilde{x}/Gz) \le -6$ . For  $-5 \le \log_{10}(\tilde{x}/Gz) \le -4$ , it is located at  $\tilde{b} = 3 \times 10^{-2}$ .