

Derivation of first term in equation (4.2) [Stiassnie(2010)]

March 3, 2020

Starting with the contribution to bottom pressure arising from the surface wave i.e. the first integral in [Stiassnie(2010)] (3.14).

$$\frac{8\rho\tilde{\zeta}_0}{\pi\tau} \int_0^\infty \frac{\mu_0 \sin(\omega\tau/2) \sin(k_0b)}{k_0^2 [2\mu_0h + \sinh(2\mu_0h)]} \cos\left(k_0x - \omega t + \frac{\omega\tau}{2}\right) d\omega \quad (0.1)$$

- $\hat{x} = \frac{x}{h}, \Rightarrow x = \hat{x}h$
- $\hat{b} = \frac{b}{h}, \Rightarrow b = \hat{b}h$
- $\hat{t} = \tilde{t} - \frac{\hat{\tau}}{2} = \sqrt{\frac{g}{h}}t - \frac{1}{2}\sqrt{\frac{g}{h}}\tau = \sqrt{\frac{g}{h}}\left(t - \frac{\tau}{2}\right), \Rightarrow t - \frac{\tau}{2} = \sqrt{\frac{h}{g}}\hat{t}$
- $\hat{\tau} = \sqrt{\frac{g}{h}}\tau, \Rightarrow \tau = \sqrt{\frac{h}{g}}\hat{\tau}$
- $\hat{k}_0 = k_0h, \Rightarrow k_0 = \frac{\hat{k}_0}{h}$
- $\hat{\omega} = \sqrt{\frac{h}{g}}\omega, \Rightarrow \omega = \sqrt{\frac{g}{h}}\hat{\omega}$ also $d\omega = \sqrt{\frac{g}{h}}d\hat{\omega}$
- $k_0 = \sqrt{\mu_0^2 + \frac{\omega^2}{c^2}},$ [Stiassnie(2010)] (3.7a) & (3.8)

Shallow water approximation implies $\frac{\omega^2}{c^2} \ll 1$, so that $\mu_0 \approx k_0$.

$$\frac{8\rho\tilde{\zeta}_0}{\pi\sqrt{\frac{h}{g}}\hat{\tau}} \operatorname{Re} \int_0^\infty \frac{\sin\left(\sqrt{\frac{g}{h}}\hat{\omega}\sqrt{\frac{h}{g}}\frac{\hat{\tau}}{2}\right) \sin\left(\frac{\hat{k}_0}{h}\hat{b}h\right)}{\frac{\hat{k}_0}{h} \left[2\frac{\hat{k}_0}{h}h + \sinh\left(2\frac{\hat{k}_0}{h}h\right)\right]} e^{i\left(\frac{\hat{k}_0}{h}\hat{x}h - \sqrt{\frac{g}{h}}\hat{\omega}\sqrt{\frac{h}{g}}\hat{t}\right)} \sqrt{\frac{g}{h}}d\hat{\omega} \quad (0.2)$$

$$\frac{8\rho g\tilde{\zeta}_0}{\pi\hat{\tau}} \operatorname{Re} \int_0^\infty \frac{\sin(\hat{\omega}\hat{\tau}/2) \sin(\hat{k}_0\hat{b})}{\hat{k}_0 \left[2\hat{k}_0 + \sinh(2\hat{k}_0)\right]} e^{i(\hat{k}_0\hat{x} - \hat{\omega}\hat{t})} d\hat{\omega} \quad (0.3)$$

The phase is given by,

$$g_0(\hat{\omega}) = \hat{k}_0(\hat{\omega}) \frac{x}{t} - \hat{\omega}. \quad (0.4)$$

Differentiation of the phase term leads to,

$$\frac{\partial g_0(\hat{\omega})}{\partial \hat{\omega}} = \frac{d\hat{k}_0(\hat{\omega})}{d\hat{\omega}} \frac{x}{t} - 1 = 0 \quad \text{at stationary point,} \quad (0.5)$$

with $\frac{d\hat{k}_0(\hat{\omega})}{d\hat{\omega}}$ obtained by differentiation of the dispersion relation $\hat{\omega}^2 = \hat{k}_0 \tanh \hat{k}_0$,

$$\frac{d\hat{k}_0(\hat{\omega})}{d\hat{\omega}} = \frac{-2\hat{\omega}}{k_0(\hat{\omega}) \tanh^2 k_0(\hat{\omega}) - \tanh k_0(\hat{\omega}) - k_0(\hat{\omega})}. \quad (0.6)$$

The stationary phase calculation requires the second derivative of $g_0(\hat{\omega})$ so differentiate 0.6 again to give,

$$\begin{aligned} \frac{d^2\hat{k}_0(\hat{\omega})}{d\hat{\omega}^2} &= \frac{-2}{\hat{k}_0(\hat{\omega}) \tanh^2 \hat{k}_0(\hat{\omega}) - \tanh \hat{k}_0(\hat{\omega}) - \hat{k}_0(\hat{\omega})} \\ &+ \frac{\left(4\hat{\omega}\hat{k}_0 \tanh \hat{k}_0(\hat{\omega}) \frac{d\hat{k}_0(\hat{\omega})}{d\hat{\omega}}\right) \left(1 - \tanh^2 \hat{k}_0(\hat{\omega})\right) + 2\hat{\omega} \tanh^2 \hat{k}_0(\hat{\omega}) \frac{d\hat{k}_0(\hat{\omega})}{d\hat{\omega}}}{\left(k_0(\hat{\omega}) \tanh^2 k_0(\hat{\omega}) - \tanh k_0(\hat{\omega}) - k_0(\hat{\omega})\right)^2} \\ &- \frac{2\hat{\omega} \frac{d\hat{k}_0(\hat{\omega})}{d\hat{\omega}} \left(1 - \tanh^2 \hat{k}_0(\hat{\omega})\right) + 2\hat{\omega} \frac{d\hat{k}_0(\hat{\omega})}{d\hat{\omega}}}{\left(k_0(\hat{\omega}) \tanh^2 k_0(\hat{\omega}) - \tanh k_0(\hat{\omega}) - k_0(\hat{\omega})\right)^2}. \end{aligned} \quad (0.7)$$

The expression 0.7 contains $\frac{d\hat{k}_0(\hat{\omega})}{d\hat{\omega}}$ terms, so to eliminate them substitute 0.6 to give,

$$\begin{aligned} \frac{d^2\hat{k}_0(\hat{\omega})}{d\hat{\omega}^2} &= \frac{8\hat{\omega}^2 \left(\hat{k}_0(\hat{\omega}) \tanh^3 \hat{k}_0(\hat{\omega})\right) - \tanh^2 \hat{k}_0(\hat{\omega}) - \hat{k}_0(\hat{\omega}) \tanh \hat{k}_0(\hat{\omega}) + 1}{\left(\hat{k}_0(\hat{\omega}) \tanh^2 \hat{k}_0(\hat{\omega}) - \tanh \hat{k}_0(\hat{\omega}) - \hat{k}_0(\hat{\omega})\right)^3} \\ &- \frac{2}{\hat{k}_0(\hat{\omega}) \tanh^2 \hat{k}_0(\hat{\omega}) - \tanh \hat{k}_0(\hat{\omega}) - \hat{k}_0(\hat{\omega})}. \end{aligned} \quad (0.8)$$

Further remove the tanh terms by substituting from the dispersion relation $\tanh \hat{k}_0(\hat{\omega}) = \frac{\hat{\omega}^2}{\hat{k}_0(\hat{\omega})}$ to arrive at,

$$\begin{aligned} \frac{d^2\hat{k}_0(\hat{\omega})}{d\hat{\omega}^2} &= \frac{8\hat{\omega}^2\hat{k}_0(\hat{\omega}) \left(-\hat{\omega}^6 + \hat{\omega}^2\hat{k}_0(\hat{\omega})^2 + \hat{\omega}^4 - \hat{k}_0(\hat{\omega})^2\right)}{\left(-\hat{\omega}^4 + \hat{k}_0(\hat{\omega})^2 + \hat{\omega}^2\right)^3} \\ &+ \frac{2\hat{k}_0(\hat{\omega})}{-\hat{\omega}^4 + \hat{k}_0(\hat{\omega})^2 + \hat{\omega}^2}. \end{aligned} \quad (0.9)$$

Finally making use of the shallow water approximation $\hat{k}_0(\hat{\omega}) = \hat{\omega}$ [Stiassnie(2010)] reduces the expression for the second derivative to,

$$\frac{d^2\hat{k}_0(\hat{\omega})}{d\hat{\omega}^2} = \frac{6\hat{\omega}^3 - 8\hat{\omega}}{(\hat{\omega}^2 - 2)^3} = \hat{\omega} + \frac{3}{4}\hat{\omega}^3 + \frac{3}{8}\hat{\omega}^5 + O(\hat{\omega}^7). \quad (0.10)$$

Which to leading order becomes,

$$\frac{d^2\hat{k}_0(\hat{\omega})}{d\hat{\omega}^2} = \hat{\omega} = \hat{\Omega}_0 \quad \text{at point of stationary phase.} \quad (0.11)$$

Therefore,

$$\frac{\partial^2 g_0(\hat{\omega})}{\partial \hat{\omega}^2} = \hat{\Omega}_0 \frac{\hat{x}}{\hat{t}}$$

Stationary phase approximation now gives,

$$\begin{aligned} & \frac{8\rho g \tilde{\zeta}_0}{\pi \hat{\tau}} \frac{\sin(\hat{\Omega}_0 \hat{\tau}/2) \sin(\hat{K}_0 \hat{b})}{\hat{K}_0 [2\hat{K}_0 + \sinh(2\hat{K}_0)]} \sqrt{\frac{2\pi}{\hat{t}}} \frac{1}{[\hat{\Omega}_0 \frac{\hat{x}}{\hat{t}}]^{\frac{1}{2}}} \cos\left(\hat{K}_0 \hat{x} - \hat{\Omega}_0 \hat{t} + \frac{\pi}{4}\right) \\ & \frac{8\rho g \tilde{\zeta}_0}{\sqrt{\pi \hat{\tau} \hat{x}^{\frac{1}{2}}}} \frac{2^{\frac{1}{2}} \sin(\hat{\Omega}_0 \hat{\tau}/2) \sin(\hat{K}_0 \hat{b})}{\hat{K}_0 \hat{\Omega}_0^{\frac{1}{2}} [2\hat{K}_0 + \sinh(2\hat{K}_0)]} \cos\left(\hat{K}_0 \hat{x} - \hat{\Omega}_0 \hat{t} + \frac{\pi}{4}\right) \end{aligned} \quad (0.12)$$

Note that,

$$\hat{K}_0 \hat{\Omega}_0^{\frac{1}{2}} = \sqrt{2} \left(\frac{\hat{t}}{\hat{x}} - 1\right)^{\frac{1}{2}} \left[\sqrt{2} \left(\frac{\hat{t}}{\hat{x}} - 1\right)^{\frac{1}{2}} \right]^{\frac{1}{2}} = 2^{\frac{1}{2}} 2^{\frac{1}{4}} \left(\frac{\hat{t}}{\hat{x}} - 1\right)^{\frac{3}{4}}$$

substituting and re-arranging 0.12 gives,

$$\begin{aligned} & \frac{8 \cdot 2^{\frac{1}{2}} \rho g \tilde{\zeta}_0}{2^{\frac{1}{2}} 2^{\frac{1}{4}} \sqrt{\pi \hat{\tau} \hat{x}^{\frac{1}{2}}}} \frac{\sin(\hat{\Omega}_0 \hat{\tau}/2) \sin(\hat{K}_0 \hat{b})}{\left(\frac{\hat{t}}{\hat{x}} - 1\right)^{\frac{3}{4}} [2\hat{K}_0 + \sinh(2\hat{K}_0)]} \cos\left(\hat{K}_0 \hat{x} - \hat{\Omega}_0 \hat{t} + \frac{\pi}{4}\right) \\ & \frac{2^{\frac{11}{4}} \rho g \tilde{\zeta}_0}{\sqrt{\pi \hat{\tau} \hat{x}^{\frac{1}{2}}}} \frac{\sin(\hat{\Omega}_0 \hat{\tau}/2) \sin(\hat{K}_0 \hat{b})}{\left(\frac{\hat{t}}{\hat{x}} - 1\right)^{\frac{3}{4}} [2\hat{K}_0 + \sinh(2\hat{K}_0)]} \cos\left(\hat{K}_0 \hat{x} - \hat{\Omega}_0 \hat{t} + \frac{\pi}{4}\right) \end{aligned} \quad (0.13)$$

Since we also have,

$$\begin{aligned} \sin(\hat{\Omega}_0 \hat{\tau}/2) &= \sin\left[\sqrt{2} \hat{\tau} \left(\frac{\hat{t}}{\hat{x}} - 1\right)^{\frac{1}{2}} / 2\right] \\ \sin(\hat{K}_0 \hat{b}) &= \sin\left[\sqrt{2} \hat{b} \left(\frac{\hat{t}}{\hat{x}} - 1\right)^{\frac{1}{2}}\right] \\ 2\hat{K}_0 &= 2\sqrt{2} \left(\frac{\hat{t}}{\hat{x}} - 1\right)^{\frac{1}{2}} = 2^{\frac{3}{2}} \left(\frac{\hat{t}}{\hat{x}} - 1\right)^{\frac{1}{2}} \end{aligned}$$

Using $\cos(-\theta) = \cos(\theta)$,

$$\begin{aligned} \cos\left[\hat{K}_0 \hat{x} - \hat{\Omega}_0 \hat{t} + \frac{\pi}{4}\right] &= \cos\left[-\left(\hat{K}_0 \hat{x} - \hat{\Omega}_0 \hat{t} + \frac{\pi}{4}\right)\right] \\ \cos\left[\hat{\Omega}_0 \hat{t} - \hat{K}_0 \hat{x} - \frac{\pi}{4}\right] &= \cos\left[\sqrt{2} \left(\frac{\hat{t}}{\hat{x}} - 1\right)^{\frac{1}{2}} \hat{t} - \sqrt{2} \left(\frac{\hat{t}}{\hat{x}} - 1\right)^{\frac{1}{2}} \hat{x} - \frac{\pi}{4}\right] \\ &= \cos\left[\sqrt{2} \left(\frac{\hat{t}}{\hat{x}} - 1\right)^{\frac{1}{2}} (\hat{t} - \hat{x}) - \frac{\pi}{4}\right] \end{aligned}$$

but,

$$(\hat{t} - \hat{x}) = \hat{x} \left(\frac{\hat{t}}{\hat{x}} - 1\right)$$

so that,

$$\cos \left[\sqrt{2} \left(\frac{\hat{t}}{\hat{x}} - 1 \right)^{\frac{1}{2}} (\hat{t} - \hat{x}) - \frac{\pi}{4} \right] = \cos \left[\sqrt{2} \hat{x} \left(\frac{\hat{t}}{\hat{x}} - 1 \right)^{\frac{3}{2}} - \frac{\pi}{4} \right]$$

so the final result is identical with the first line of equation (4.2) in [Stiassnie(2010)] with the exception of an extra factor of 2 in the numerator.

$$2^{\frac{7}{4}} \cdot 2 = 2^{\frac{7}{4}} \cdot 2^{\frac{4}{4}} = 2^{\frac{11}{4}}$$

In summary the first line of equation (4.2) in [Stiassnie(2010)] is given as,

$$\frac{2^{\frac{7}{4}} \rho g \tilde{\zeta}_0 \sin \left[\sqrt{2} \hat{\tau} \left(\frac{\hat{t}}{\hat{x}} - 1 \right)^{\frac{1}{2}} / 2 \right] \sin \left[\sqrt{2} \hat{b} \left(\frac{\hat{t}}{\hat{x}} - 1 \right)^{\frac{1}{2}} \right] \cos \left[\sqrt{2} \hat{x} \left(\frac{\hat{t}}{\hat{x}} - 1 \right)^{\frac{3}{2}} - \frac{\pi}{4} \right]}{\sqrt{\pi} \hat{\tau} \hat{x}^{\frac{1}{2}} \left(\frac{\hat{t}}{\hat{x}} - 1 \right)^{\frac{3}{4}} \left[2^{\frac{3}{2}} \left(\frac{\hat{t}}{\hat{x}} - 1 \right)^{\frac{1}{2}} + \sinh \left(2^{\frac{3}{2}} \left(\frac{\hat{t}}{\hat{x}} - 1 \right)^{\frac{1}{2}} \right) \right]}}, \quad (0.14)$$

but should read,

$$\frac{2^{\frac{11}{4}} \rho g \tilde{\zeta}_0 \sin \left[\sqrt{2} \hat{\tau} \left(\frac{\hat{t}}{\hat{x}} - 1 \right)^{\frac{1}{2}} / 2 \right] \sin \left[\sqrt{2} \hat{b} \left(\frac{\hat{t}}{\hat{x}} - 1 \right)^{\frac{1}{2}} \right] \cos \left[\sqrt{2} \hat{x} \left(\frac{\hat{t}}{\hat{x}} - 1 \right)^{\frac{3}{2}} - \frac{\pi}{4} \right]}{\sqrt{\pi} \hat{\tau} \hat{x}^{\frac{1}{2}} \left(\frac{\hat{t}}{\hat{x}} - 1 \right)^{\frac{3}{4}} \left[2^{\frac{3}{2}} \left(\frac{\hat{t}}{\hat{x}} - 1 \right)^{\frac{1}{2}} + \sinh \left(2^{\frac{3}{2}} \left(\frac{\hat{t}}{\hat{x}} - 1 \right)^{\frac{1}{2}} \right) \right]}}. \quad (0.15)$$

A similar derivation applies to the first term in equation (4.1) of [Stiassnie(2010)] relating to the surface elevation.

References

[Stiassnie(2010)] STIASSNIE, M. 2010 Tsunamis and acoustic-gravity waves from underwater earthquakes. *Journal of Engineering Mathematics* **67** (1-2), 23–32.