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Appendix to the paper "On the Creeping Motion of Two Arbitrary Sized Touching Spheres in a Linear Shear Field", by A. Nir and A. Acrivos.

I. The Solution of the Equations of Motion for Arbitrary-Sized Spheres in a Linear Flow Field.

Here we describe the procedure used in the above paper for the solution of the functions  $A_{m}(\nu)$  to  $H_{m}(\nu)$ .

Let  $V_r^N$ ,  $V_{\tilde{\phi}}^N$  and  $V_z^N$ , the cylindrical components of the velocities  $\underline{V}^N$  at the surface of the  $N^{th}$  sphere, be expanded as

$$\begin{pmatrix} \mathbf{v}_{\mathbf{r}}^{N} \\ \mathbf{v}_{\mathbf{r}}^{N} \end{pmatrix} = \sum_{\mathbf{m}=\mathbf{o}}^{\infty} \left\{ \begin{pmatrix} \mathbf{R}_{\mathbf{m}}^{N} \\ \mathbf{Z}_{\mathbf{m}}^{N} \end{pmatrix} \sin \mathbf{m} \hat{\boldsymbol{\phi}} + \begin{pmatrix} \mathbf{R}_{-\mathbf{m}}^{N} \\ \mathbf{Z}_{-\mathbf{m}}^{N} \end{pmatrix} \cos \mathbf{m} \hat{\boldsymbol{\phi}} \right\}$$

$$\mathbf{v}_{\hat{\boldsymbol{\phi}}}^{N} = \sum_{\mathbf{m}=\mathbf{o}}^{\infty} \left\{ \frac{1}{\mathbf{m}} \Phi_{\mathbf{m}}^{N} \frac{\partial}{\partial \hat{\boldsymbol{\phi}}} \sin \mathbf{m} \hat{\boldsymbol{\phi}} + \frac{1}{\mathbf{m}} \Phi_{-\mathbf{m}}^{N} \frac{\partial}{\partial \hat{\boldsymbol{\phi}}} \cos \mathbf{m} \hat{\boldsymbol{\phi}} \right\}$$
(A1)

where  $R_{m}^{N}$ ,  $\Phi_{m}^{N}$  and  $Z_{m}^{N}$  are only functions of  $\eta$ . When the components of (A1) are equated to the corresponding components of (2.5), evaluated on the surface  $\xi = \xi_{N}$ , the following relations for the various auxiliary functions replace the no-slip requirement (2.4)

$$\pi_{m} = \frac{2}{z} Z_{m}^{N} - \frac{2}{z} w_{m}$$

$$v_{m} = R_{m}^{N} + \Phi_{m}^{N} - \frac{r}{z} Z_{m}^{N} + \frac{r}{z} w_{m}$$

$$u_{m} = R_{m}^{N} - \Phi_{m}^{N} - \frac{r}{z} Z_{m}^{N} + \frac{r}{z} w_{m}$$

$$at \xi = \xi_{N}$$
(A2)

These, together with (2.7) and its equivalents, constitute implicit relations between the various function coefficients A to H m.

For convenience in further evaluations we define

$$P_{A}(\nu) = \frac{\sinh \lambda \nu \alpha \cosh \nu \alpha}{\sinh (\lambda + 1) \nu \alpha}$$

$$P_{B}(\nu) = \frac{\sinh \nu \alpha \cosh \lambda \nu \alpha}{\sinh (\lambda + 1) \nu \alpha}$$

$$Q_{A}(\nu) = \frac{\cosh \nu \alpha \cosh \lambda \nu \alpha}{\sinh (\lambda + 1) \nu \alpha}$$

$$Q_{B}(\nu) = \frac{\sinh \nu \alpha \sinh \lambda \nu \alpha}{\sinh (\lambda + 1) \nu \alpha}$$
(A3)

where  $\lambda$  is the size-ratio of the two spheres.

Rearrangement of the expressions in (A2) by use of the differential equation and recurrence relations satisfied by  $J_{m}(\nu\eta)$ , followed by an integration by parts and application of the Hankel transform from the  $\eta$  space to the  $\nu$  domain, yield finally the desired functional dependence of  $C_{m}$  -  $H_{m}$  on  $A_{m}$  and  $B_{m}$ ,

$$C_{\mathbf{m}} = C_{\mathbf{m}} + \frac{2(1-\mathbf{m}^2)}{\nu^2 \alpha} \left[ \left( 1 - \frac{\lambda+1}{\lambda} P_{\mathbf{B}} \right) A_{\mathbf{m}} + \left( \frac{\lambda+1}{\lambda} Q_{\mathbf{B}} - \frac{\nu \alpha}{1-\mathbf{m}^2} \right) B_{\mathbf{m}} \right] - \frac{2}{\nu \alpha} \left[ \left( 1 - \frac{\lambda+1}{\lambda} P_{\mathbf{B}} \right) A_{\mathbf{m}}^{\dagger} \right]$$

$$+\left(\frac{\lambda+1}{\lambda}Q_{B}-2\nu\alpha\right)B_{m}^{\dagger}+\frac{2}{\alpha}\left[\left(1-\frac{\lambda+1}{\lambda}P_{B}\right)A_{m}^{\dagger\prime}+\frac{\lambda+1}{\lambda}Q_{B}B_{m}^{\dagger\prime}\right]$$

$$\mathbf{E}_{\mathbf{m}} = \mathbf{E}_{\mathbf{m}} + \frac{\mathbf{m}-1}{\nu\alpha} \left[ \left( 1 - \frac{\lambda+1}{\lambda} \mathbf{P}_{\mathbf{B}} \right) \mathbf{A}_{\mathbf{m}} + \left( \frac{\lambda+1}{\lambda} \mathbf{Q}_{\mathbf{B}} + \frac{\nu\alpha}{\mathbf{m}-1} \right) \mathbf{B}_{\mathbf{m}} \right] + \frac{1}{\alpha} \left[ \left( 1 - \frac{\lambda+1}{\lambda} \mathbf{P}_{\mathbf{B}} \right) \mathbf{A}_{\mathbf{m}}^{\dagger} + \frac{\lambda+1}{\lambda} \mathbf{Q}_{\mathbf{B}} \mathbf{B}_{\mathbf{m}}^{\dagger} \right]$$

$$G_{\mathbf{m}} = G_{\mathbf{m}} + \frac{\mathbf{m}+1}{\nu\alpha} \left[ \left( 1 - \frac{\lambda+1}{\lambda} P_{\mathbf{B}} \right) A_{\mathbf{m}} + \left( \frac{\lambda+1}{\lambda} Q_{\mathbf{B}} - \frac{\nu\alpha}{\mathbf{m}-1} \right) B_{\mathbf{m}} \right] - \frac{1}{\alpha} \left[ \left( 1 - \frac{\lambda+1}{\lambda} P_{\mathbf{B}} \right) A_{\mathbf{m}}^{\dagger} + \frac{\lambda+1}{\lambda} Q_{\mathbf{B}} B_{\mathbf{m}}^{\dagger} \right] ,$$

together with similar expressions for  $D_m$ ,  $F_m$  and  $H_m$  in which the set  $(C_m, C_m, C_m, P_B, Q_B, A_m, B_m)$  is replaced by, respectively,  $(D_m, T_m, T_m, P_A, Q_A, B_m, A_m)$ , and the prime denotes differentiation with respect to  $\nu$ . (2.10) now follows readily.

In (A4) the known integrals resulting from the transformation are

$$\begin{pmatrix} \zeta_{m} \\ \mathcal{D}_{m} \end{pmatrix} = 2\nu \begin{pmatrix} Q_{B} \cosh \nu \alpha \\ Q_{A} \operatorname{sech} \nu \alpha \end{pmatrix} \int_{0}^{\infty} \frac{\eta(\alpha^{2} + \eta^{2})^{\frac{1}{2}}}{\alpha} Z_{m}^{I} J_{m}(\nu \eta) d\eta$$

$$= 2\nu \begin{pmatrix} Q_{B} \cosh \lambda \nu \alpha \\ Q_{A} \operatorname{sech} \lambda \nu \alpha \end{pmatrix} \int_{0}^{\infty} \frac{\eta(\lambda^{2} + \eta^{2})^{\frac{1}{2}}}{\lambda \alpha} Z_{m}^{II} J_{m}(\nu \eta) d\eta$$

$$\begin{pmatrix} \mathcal{E}_{m} \\ \mathcal{T}_{m} \end{pmatrix} = \nu \begin{pmatrix} Q_{B} \cosh \nu \alpha \\ Q_{A} \operatorname{sech} \nu \alpha \end{pmatrix} \int_{0}^{\infty} \frac{\eta}{\left(\alpha^{2} + \eta^{2}\right)^{\frac{1}{2}}} \left( R_{m}^{I} + \Phi_{m}^{I} - \frac{\eta}{\alpha} Z_{m}^{I} \right) J_{m-1}(\nu \eta) d\eta$$

$$+ \nu \begin{pmatrix} Q_{B} \cosh \lambda \nu \alpha \\ Q_{A} \operatorname{sech} \lambda \nu \alpha \end{pmatrix} \int_{0}^{\infty} \frac{\eta}{\left(\lambda^{2} \alpha^{2} + \eta^{2}\right)^{\frac{1}{2}}} \left( R_{m}^{II} + \Phi_{m}^{II} + \frac{\eta}{\lambda \alpha} Z_{m}^{II} \right) J_{m-1}(\nu \alpha) d\eta$$

$$(A5)$$

$$\begin{pmatrix} \mathcal{F}_{m} \\ \mathcal{J}_{m} \end{pmatrix} = \nu \begin{pmatrix} Q_{B} \cosh \nu \alpha \\ Q_{A} \operatorname{sech} \nu \alpha \end{pmatrix} \int_{0}^{\infty} \frac{\eta}{\left(\alpha^{2} + \eta^{2}\right)^{\frac{1}{2}}} \left(R_{m}^{I} - \Phi_{m}^{I} - \frac{\eta}{\alpha} Z_{m}^{I}\right) J_{m+1}(\nu \eta) d\eta$$

$$\pm \nu \left( \begin{array}{c} Q_{\rm B} \cosh \lambda \nu \alpha \\ Q_{\rm A} \operatorname{sech} \lambda \nu \alpha \end{array} \right) \int_{0}^{\infty} \frac{\eta}{\left(\lambda^{2} \alpha^{2} + \eta^{2}\right)^{\frac{1}{2}}} \left( R_{\rm m}^{\rm I} - \Phi_{\rm m}^{\rm II} + \frac{\eta}{\lambda \alpha} Z_{\rm m}^{\rm II} \right) J_{\rm m+1}(\nu \alpha) d\eta .$$

Their explicit expressions, obtained with the use of the following definite integrals

$$\nu \int_{0}^{\infty} \frac{\eta J_{0}(\nu \eta)}{(\alpha^{2} + \eta^{2})^{\frac{1}{2}}} d\eta = \frac{\nu^{2}}{1 + \nu \alpha} \int_{0}^{\infty} \frac{\eta^{2} J_{1}(\nu \eta)}{(\alpha^{2} + \eta^{2})^{\frac{1}{2}}} d\eta = \frac{\nu^{3}}{3 + 3\nu \alpha + \nu^{2} \alpha^{2}} \int_{0}^{\infty} \frac{\eta^{3} J_{2}(\nu \eta)}{(\alpha^{2} + \eta^{2})^{\frac{1}{2}}} d\eta = \ell^{-\nu \alpha} \quad (A6)$$

and related expressions arrived at by differentiation of (A6) with respect to  $\alpha$  or  $\nu$ , are given in Table A1.

When the above expressions, (A5), together with (A4) are substituted into (2.9), the explicit form of (2.11) is found

$$\begin{split} & \left[ \nu P_{A}^{\prime} + \left( \frac{\lambda}{\lambda + 1} - P_{A} \right) \right] B_{m}^{\prime\prime\prime} + \left[ -\nu Q_{A}^{\prime} + Q_{A} \right] A_{m}^{\prime\prime\prime} + \left[ \nu P_{A}^{\prime\prime\prime} + P_{A}^{\prime} - \frac{1}{\nu} \left( \frac{\lambda}{\lambda + 1} - P_{A} \right) \right] B_{m}^{\prime\prime} \\ & + \left[ -\nu Q_{A}^{\prime\prime\prime} - Q_{A}^{\prime} - \frac{Q_{A}}{\nu} + \frac{2\lambda\alpha}{\lambda + 1} \right] A_{m}^{\prime} + \left[ -P_{A}^{\prime\prime\prime} - \frac{1}{\nu} \left( 1 + m^{2} \right) P_{A}^{\prime} + \frac{1}{\nu^{2}} \left( 1 - m^{2} \right) \left( \frac{\lambda}{1 + \lambda} - P_{A} \right) \right] B_{m} \\ & + \left[ Q_{A}^{\prime\prime\prime} + \frac{1}{\nu} \left( 1 + m^{2} \right) Q_{A}^{\prime} + \frac{1}{\nu^{2}} \left( 1 - m^{2} \right) Q_{A} - \frac{2\lambda\alpha}{\nu(\lambda + 1)} \right] A_{m} = \frac{\lambda\alpha}{2(\lambda + 1)} \mathcal{J}_{m} \end{split}$$

$$(A7)$$

together with a similar equation in which the set  $(A_m, B_m, P_A, Q_A, \mathcal{N}_m)$  is replaced by, respectively,  $(B_m, A_m, P_B, Q_B, \mathcal{N}_m)$ . The various inhomogeneous terms are given in Table A1.

To solve (A7) we examine the asymptotic behavior of  $\bullet$  its solutions. As  $\nu \to 0$  the form of the equations is

$$\frac{4}{\lambda \alpha^{2}} \left[ A_{m}^{"} - \frac{1}{\nu} A_{m}^{!} + \frac{(1-m^{2})}{\nu^{2}} A_{m} \right] - \frac{2(\lambda-1)\alpha}{3} \left[ \nu^{3} B_{m}^{"} + 5 \nu^{2} B_{m}^{!} - (5+m^{2}) \nu B_{m} \right] = K_{m}(\nu) + O(\nu^{n})$$
and

(A8)

$$\frac{2(\lambda-1)}{\lambda\alpha} \left[ \frac{1}{\nu} A_{m}^{"} - \frac{1}{\nu^{2}} A_{m}^{"} + \frac{(1-m^{2})}{\nu^{3}} A_{m} \right] + \frac{4\lambda\alpha^{2}}{3} \left[ \nu^{2} B_{m}^{"} + 5\nu B_{m}^{"} - (5+m^{2}) B_{m}^{"} \right] = L_{m}(\nu) + O(\nu^{n})$$

while, as  $\nu \to \infty$ 

$$\frac{\lambda+1}{\lambda\alpha} \left[ A_{m}^{"} + \frac{4\lambda\alpha}{\lambda+1} A_{m}^{!} - \frac{4\lambda\alpha}{\lambda+1} A_{m} \right] + \frac{\lambda-1}{\lambda\alpha} \left[ B_{m}^{"} - \frac{1}{\nu} B_{m}^{"} + \frac{1-m^{2}}{\nu^{2}} B_{m} \right] = S_{m}(\nu) e^{-2\nu\alpha} + O(e^{-2\lambda\nu\alpha}) + O(e^{-4\nu\alpha})$$
and
$$\frac{\lambda-1}{\lambda\alpha} \left[ A_{m}^{"} - \frac{1}{\nu} A_{m}^{"} + \frac{(1-m^{2})}{\nu^{2}} A_{m} \right] + \frac{\lambda+1}{\lambda\alpha} \left[ B_{m}^{"} + \frac{4\lambda\alpha}{\lambda+1} B_{m}^{"} - \frac{4\lambda\alpha}{\lambda+1} B_{m} \right] = T_{m}(\nu) e^{-2\nu\alpha} + O(e^{-2\lambda\alpha}) + O(e^{-4\nu\alpha})$$

where the coefficients of the polynomials K, L, S and T depend on e ij and  $(\Omega_i - \omega_i)$ , and n is determined by their truncation. The leading terms in the first order approximation to the homogeneous solutions  $(A_{mh}, B_{mh})$  and the particular solutions  $(A_{mp}, B_{mp})$ 

$$A_{mh} = \nu^{1+m}, A_{op} = O(\nu), A_{\pm 1p} = O(\nu), A_{\pm 2} = O(\nu^{5})$$

$$B_{mh} = \nu^{-2 \pm \sqrt{9+m^{2}}}, B_{op} = -\frac{24\lambda}{(\lambda+1)^{3}}, B_{\pm 1p} = -\frac{2}{3} \frac{(\lambda-1)}{(\lambda+1)^{2}}, B_{\pm 2} = O(\nu^{2})$$
(A10)

for (A8), and

$$A_{mh} = B_{mh} = (\nu, e^{-2\nu\alpha}), A_{mp} = O(S_{m}e^{-2\nu\alpha}), B_{mp} = O(T_{m}e^{-2\nu\alpha})$$
 (A11)

for (A9) provide then the appropriate boundary conditions for the numerical solution in view of (2.10) and the requirement that both  $A_{m}$  and  $B_{m}$  decay exponentially for large  $\nu$ .

The above system was solved numerically as a boundary value problem by representing the derivatives in the usual finite differences scheme which, in turn, yields

$$\overset{\times}{\mathbb{Z}} \overset{\times}{\mathbb{Y}} + \overset{\times}{\mathbb{Z}} \overset{Z}{\mathbb{Z}} = \overset{\Sigma}{\mathbb{Z}}$$
(A12)

where Y, Z,  $\Sigma$  and W are the vectors of the values of  $A_m$ ,  $B_m$ ,  $A_m$  and  $A_m$  at the grid points and X,  $A_m$ ,  $A_m$  and  $A_m$  represent the matrix forms of the linear operators of (A7). It was found possible to avoid a straightforward solution of (A12), which would have involved inverting a complicated matrix, and to by-pass numerical instabilities, which, in view of (A8), arise in the regions  $\lambda \to 1$  and  $\lambda \to \infty$  as  $\gamma \to 0$ , by the use of the simple iterative procedure

$$\widetilde{\mathcal{Z}} = \underbrace{\widetilde{\mathcal{Z}}_{(n+1)}}_{(n+1)} = \underbrace{\widetilde{\mathcal{Z}}}_{(n+1)} = \underbrace{\widetilde{\mathcal{Z}}}_{(n+1)} = \underbrace{\widetilde{\mathcal{Z}}_{(n+1)}}_{(n+1)} = \underbrace{\widetilde{\mathcal{Z}}}_{(n+1)} = \underbrace{\widetilde{\mathcal{Z}}_{(n+1)}}_{(n+1)} = \underbrace{\widetilde{\mathcal{Z}_{(n+1)}}_{(n+1)}}_{(n+1)} = \underbrace{\widetilde{\mathcal{Z}}_{(n+1)}}_{(n+1)} = \underbrace{\widetilde{\mathcal{Z}}_{(n+1)}}_{(n+1)} = \underbrace{\widetilde{\mathcal{Z}}_{(n+1)}}_{(n+1)} = \underbrace{\widetilde{\mathcal{Z}}_{(n+1)}}_{(n+1)} = \underbrace{\widetilde{\mathcal{Z}}_{(n+1)}}_{(n+1)} = \underbrace{\widetilde{\mathcal{Z}}_{(n+1)}}_$$

where n is the iteration number.

Table A1: The explicit expressions for the integrals in (A5) and the inhomogeneous terms in (A7) (for  $U_3 = -\zeta e_{33}$ )\*

$$\oint_{0} = \left[ 10 \, \nu \, (P_{\rm B}^{\scriptscriptstyle \rm I} - P_{\rm A}^{\scriptscriptstyle \rm I}) \, + 3 \, \nu^{2} \, (P_{\rm B}^{\scriptscriptstyle \rm II} - P_{\rm A}^{\scriptscriptstyle \rm II}) \right] \, \, {\rm e}_{33}$$

$$\Re _{o} = (20 \nu Q_{B}^{1} + 6 \nu^{2} Q_{B}^{11}) e_{33}$$

$$c_0 = -2(1-2Q_B) e_{33}$$

$$\int_{0}^{\infty} e^{-2(P_B - P_A) e_{33}}$$

$$\xi_{o} = -\nu (1-2Q_{B}) (\Omega_{3}-\omega_{3} + \frac{3}{2}e_{33})$$

$$\mathcal{F}_{o} = \nu (P_{B} - P_{A}) (\Omega_{3} - \omega_{3} + \frac{3}{2} e_{33})$$

$$c_0 = -\nu(1-2Q_B)(\Omega_3 - \omega_3 - \frac{3}{2}e_{33})$$

$$\mathcal{I}(_{o} = \nu(P_{B} - P_{A}) (\Omega_{3} - \omega_{3} - \frac{3}{2} e_{33})$$

$$\int_{-1}^{2} = -\left[\frac{2}{\nu\alpha}(1-2Q_{A})+4(\nu+\frac{1}{\alpha})Q_{A}^{\dagger} - \frac{2}{\nu\alpha}\left(\frac{\lambda-1}{\lambda}\right)(P_{A}-Q_{A}-\nu P_{A}^{\dagger}+\nu Q_{A}^{\dagger})-2\zeta\nu\left(P_{B}^{\dagger\prime}-P_{A}^{\dagger\prime}\right)\right](\Omega_{2}-\omega_{2})$$

$$-\left[\frac{2}{\nu\alpha}(1-2Q_{A})+4(5\nu+\frac{1}{\alpha})Q_{A}^{\dagger}+8\nu^{2}Q_{A}^{\dagger\prime} - \frac{2}{\nu\alpha}\left(\frac{\lambda-1}{\lambda}\right)(P_{A}-Q_{A}-\nu P_{A}^{\dagger}+\nu Q_{A}^{\dagger})+2\zeta\nu(P_{B}^{\dagger\prime}-P_{A}^{\dagger\prime})\right] e_{13}$$

$$\int_{-1}^{2} = -\left[\frac{2}{\nu\alpha}(P_{B}^{-}P_{A}^{-}) - 2(\nu + \frac{1}{\alpha})(P_{B}^{'} - P_{A}^{'}) - \frac{2}{\nu\alpha}\left(\frac{\lambda - 1}{\lambda}\right)(P_{B}^{-}Q_{B}^{-}\nu P_{B}^{'} + \nu Q_{B}^{'}) - 4\zeta\nu Q_{B}^{''}\right] (\Omega_{2}^{-}\omega_{2}^{-})$$

$$-\left[\frac{2}{\nu\alpha}(P_{B}^{-}P_{A}^{-}) - 2(5\nu + \frac{1}{\alpha})(P_{B}^{'} - P_{A}^{'}) - 4\nu^{2}(P_{B}^{''} - P_{A}^{''}) - \frac{2}{\nu\alpha}\left(\frac{\lambda - 1}{\lambda}\right)(P_{B}^{-}Q_{B}^{-}\nu P_{B}^{'} + \nu Q_{B}^{'}) + 4\zeta\nu Q_{B}^{''}\right] e$$

\*for m = +1 replace  $\Omega_2$ - $\omega_2$  by  $-\Omega_1$  +  $\omega_1$  and  $e_{13}$  by  $e_{23}$  in expressions with m = -1; similarly, for m = +2 replace  $e_{11}$ - $e_{22}$  by  $2e_{12}$  in m = -2.

Table Al: Continued